

BPINN-EM-Post: Bayesian Physics-Informed Neural Network based Stochastic Electromigration Damage Analysis in the Post-void Phase

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Abstract— Electromigration (EM)-induced stress evolution is inherently non-deterministic due to input current fluctuations and manufacturing non-idealities. Existing approaches for estimating stress variations rely on computationally expensive Monte Carlo simulations with industrial solvers. This work presents *BPINN-EM-Post*, a framework for stochastic analysis of EM-induced post-voiding aging processes. The key contributions are: (1) We integrate closed-form analytical solutions with a Bayesian Physics-Informed Neural Network (BPINN) to accelerate stochastic EM analysis. The closed-form solutions enforce physical laws at individual wire segments, while BPINN satisfies physics constraints at inter-segment junctions and captures stochastic behaviors. (2) By reducing loss function variables through analytical solutions, training efficiency improves substantially without sacrificing accuracy, and variational effects are naturally incorporated. (3) The analytical solutions address the challenge of incorporating initial stress distributions during post-void stress calculations. Experimental results show that *BPINN-EM-Post* achieves over 240× and 67× speedup compared to Monte Carlo simulations using FEM-based COMSOL and FDM-based EMSpice, respectively, with marginal accuracy loss.

Index Terms—Post-void Electromigration (EM), Physics informed neural network (PINN), Bayesian networks

I. INTRODUCTION

Electromigration (EM) is the transport of metal atoms in on-chip interconnects driven by momentum transfer from high-density electron flow, and is a major reliability concern for VLSI interconnects. Divergence of atomic flux induces hydrostatic stress—compressive at the anode and tensile at the cathode. When the local stress exceeds a critical threshold, voids may nucleate and grow near the cathode or hillocks may form near the anode, potentially leading to open or short failures. EM lifetime is commonly quantified by the mean time to failure (MTTF), which captures stochastic variability arising from materials, geometry, and operating conditions [1].

Traditionally, the MTTF or reliability of an interconnect wire is linked to the wire's current density through well-established EM models by Black and Blech [2], [3]. However, these single-wire segment EM models have been increasingly criticized for being overly conservative, as they treat each wire segment in isolation. Recent research demonstrates that stress evolution among wire segments within an EM tree, is highly correlated and should be analyzed collectively [4], [5]. Numerous physics-based analytical and numerical solutions have

been proposed to address the above-mentioned limitations [6]–[15]. These methods primarily focus on solving Korhonen's partial differential equation (PDE) to model EM-induced stress evolution [16]. Nevertheless, traditional numerical techniques for solving Korhonen's equation and related PDEs remain computationally costly. Furthermore, stochastic physics-based EM analyses using Monte Carlo simulations are prohibitively expensive for numerical solvers such as COMSOL [17] and EMSpice [13], which demand multiple samplings to estimate variation distributions.

In recent years, machine learning-based methods have demonstrated strong effectiveness and efficiency in addressing complex EDA problems [18]–[21]. Among them, physics-informed neural networks (PINN) has been developed to facilitate the learning and integration of physical laws represented by nonlinear PDEs in complex physical, biological, and engineering systems [22], [23]. PINN approach has been utilized to solve Korhonen's equation, showing promising results for EM stress modeling [24]–[26].

Conventional PINN-based EM solvers enforce physical laws, boundary conditions (BCs), and initial conditions (ICs) via loss functions, which can be effective on small PDE domains but tend to scale poorly and do not capture stochastic variability. Recent hierarchical PINN schemes accelerate EM analysis by splitting the problem into nucleation and post-voiding phases [25], [27], reducing the number of variables and improving scalability on large interconnect trees; however, these methods remain largely deterministic and do not quantify uncertainty. While Bayesian neural networks (BNNs) provide principled uncertainty quantification [28] and have been combined with PINNs for the nucleation phase [29], extending them to the post-voiding phase is challenging due to the need to incorporate the initial stress distribution carried over from nucleation, which is complex and often infeasible for standard neural architectures [27].

To overcome these limitations, we introduce *BPINN-EM-Post*, a boundary physics-informed Bayesian neural network tailored for the post-voiding phase. *BPINN-EM-Post* couples closed-form analytical stress solutions for individual segments with a lightweight boundary PINN that optimizes only inter-segment atomic fluxes while enforcing stress continuity and atomic flux conservation. This hybrid design removes the need to parametrize the full initial stress field, drastically reduces

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the number of trainable variables, and enables fast posterior sampling. The Bayesian component provides distributions over flux and stress, yielding accurate variational modeling with strong scalability to large EM trees and substantial computational speedups. Our major contributions are as follows:

- We introduce **BPINN-EM-Post**, the first boundary physics-informed Bayesian neural network for stochastic EM stress evolution in multi-segment interconnect trees during the post-voiding phase.
- We hybridize closed-form analytical segment solutions with a lightweight boundary PINN that trains only inter-segment atomic fluxes while enforcing stress continuity and flux conservation via a compact loss.
- The design eliminates parametrization of the full initial stress field inherited from nucleation, reduces trainable variables, and enables fast posterior sampling.
- The Bayesian formulation yields calibrated uncertainty (posterior distributions) over stress and flux, supporting accurate variational modeling and scalability to large EM trees.
- Numerical results show more than $240\times$ speedup versus Monte Carlo with FEM-based COMSOL and $> 67\times$ versus FDM-based EMSpice, with $< 1\%$ error.

This paper is organized as follows. Section II surveys related work. Section III reviews EM stress evolution during the post-voiding phase and discusses variation estimation. Section IV details the proposed **BPINN-EM-Post** framework. Section V presents numerical results, and Section VI concludes the paper.

II. RELATED WORK

The variational or stochastic electromigration (EM) analysis on interconnect lifetime has been extensively studied. Research in [30] demonstrates that continued technology scaling degrades both the mean time to failure (MTTF) and failure-time distributions, underscoring persistent reliability challenges in advanced interconnects. Early work by Li *et al.* [1] introduced variability into EM analysis for single wire segments, employing analytical and numerical techniques to estimate time to failure. Two sources of uncertainty were considered: circuit-level variability, treating wire resistance as a random variable (RV), and geometry-level variability, modeling lithography-induced imperfections such as bumps and necking as RVs.

Variability in power-grid networks was later examined in [31], which analyzed both global and local process variations using a Hermite polynomial chaos framework and estimated lifetime via Black's law. A more comprehensive grid-level treatment was presented in [32], where Korhonen's PDE is solved using finite differences, EM diffusivity is modeled as an RV, and Monte Carlo analysis—augmented with *ad hoc* acceleration heuristics—is applied to capture stochastic EM behavior. More recently, [33] investigated variability arising from stochastic input currents, modeling functional-block current waveforms and computing variances and covariances through large-scale matrix solutions across the grid, a process that remains computationally demanding.

Recent Work in [34] introduced a Bayesian PINN framework aimed at quantifying noise in observations and addressing the overfitting challenges typical of standard PINNs, and showed effectiveness on standard, relatively straightforward problems. Lamichhane *et al.* [29] proposed a hierarchical approach combining a pretrained Bayesian network with a physics-informed neural network (PINN) to estimate variation in EM-induced stress, marking a data-drive direction in stochastic EM analysis.

However, extending Bayesian PINNs to the post-voiding phase remains challenging due to the need to incorporate complex initial stress distributions inherited from the nucleation phase, which are difficult to parametrize with standard neural architectures [27]. In this paper, we propose **BPINN-EM-Post**, combining analytical solutions with Bayesian PINN for efficient variation estimation in multi-segment interconnects, achieving significant speedup over Monte Carlo simulations. Following [33], we focus on stochastic EM stress from current density fluctuations.

III. PRELIMINARIES

In this section, we provide a brief overview of EM stress evolution during the post-voiding phase in multi-segment interconnects, followed by a discussion on the estimation of variations in EM stress evolution.

A. EM Stress Evolution in Post-voiding Phase

In confined metal wires subjected to high current densities, EM occurs as atoms are migrated from the cathode to the anode due to interactions between electrons and metal atoms [2]. Over time, this atom migration may potentially cause void and hillock formations that compromise interconnect functionality.

Recently, physics-based EM models based on Korhonen's equation [16] has been proposed to addresses the limitations of existing empirical EM models such as Blech's limit [3] and Black's MTTF [2]. The new model describes the hydrostatic stress evolution in a confined multi-segment metal wire with material block boundary conditions as shown in Eq. (1), where $\sigma_{ij}(x, t)$ represents the stress in the interconnect segment ij connecting nodes i and j .

$$\begin{aligned}
 PDE : \frac{\partial \sigma_{ij}(x, t)}{\partial t} &= \frac{\partial}{\partial x} \left[\kappa_{ij} \left(\frac{\partial \sigma_{ij}(x, t)}{\partial x} + G_{ij} \right) \right], \quad t > 0 \\
 BC : \sigma_{ij_1}(x_i, t) &= \sigma_{ij_2}(x_i, t), \quad t > 0 \\
 BC : \sum_{ij} \kappa_{ij} \left(\frac{\partial \sigma_{ij}(x, t)}{\partial x} \right) \Big|_{x=x_r} &+ G_{ij} \cdot n_r = 0, \quad t > 0 \\
 BC : \kappa_{ij} \left(\frac{\partial \sigma_{ij}(x, t)}{\partial x} \right) \Big|_{x=x_b} &+ G_{ij} = 0, \quad t > 0 \\
 IC : \sigma_{ij}(x, 0) &= \sigma_{ij,T}
 \end{aligned} \tag{1}$$

where G_{ij} denotes the EM driving force in segment ij , calculated as $G_{ij} = \frac{e\rho J_{ij} Z^*}{\Omega}$, where J_{ij} is the current density in segment ij . The stress diffusivity denoted as κ_{ij} is defined by $\kappa_{ij} = D_a B \Omega / (k_B T)$, where D_a is the effective atomic diffusion coefficient, B is the effective bulk modulus, k_B is Boltzmann's constant, T is the absolute temperature, and E_a

is the EM activation energy. e is the electron charge, ρ is resistivity, and Z^* is the effective charge.

The first BC (Dirichlet BC) in Eq. (1) enforces stress continuity at inter-segment junctions, specifically at $x = x_r$. The second BC (Neumann BC) addresses atomic flux conservation at these junctions, while the third BC (Neumann BC) applies to blocking terminal boundaries $x = x_b$, ensuring zero atomic flux. The inward unit normal direction at the interior junction node x_r on segment ij is represented by n_r . The IC specifies that the initial stress distribution in segment ij is given by $\sigma_{ij,T}$.

In multi-segment interconnect trees, void nucleation occurs at the cathode when the steady-state nucleation stress surpasses the critical stress σ_{crit} . This moment marks the nucleation time, denoted as t_{nuc} . Beyond this time, $t > t_{nuc}$, the void enlarges and the dynamics of stress evolution diverge from nucleation phase. Once nucleated, the stress at the interface of the void dramatically drops to zero [7] due to stress relaxation.

For the segment where the void originates, the equations governing the post-voiding phase are presented in Eq. (2) [7], which assumes the $x = x_{nuc}$ node as the cathode where the void forms. The parameter δ represents the effective thickness of the void interface. This boundary condition ensures that both the stress and material flux (derivative of stress) at the void location approach zero within a short period, thereby modeling the stress relaxation following void formation. Note that the initial condition (IC) in Eq. (2) uses the stress profile at nucleation time t_{nuc} as the starting point for the post-voiding stress evolution analysis.

$$\begin{aligned}
PDE: \quad & \frac{\partial \sigma(x, t)}{\partial t} = \frac{\partial}{\partial x} \left[\kappa \left(\frac{\partial \sigma(x, t)}{\partial x} + G \right) \right], \quad t > 0 \\
BC: \quad & \left. \frac{\partial \sigma(0, t)}{\partial x} \right|_{x=x_{nuc}} = \frac{\sigma(0, t)}{\delta}, \quad t > 0 \\
BC: \quad & \left. \frac{\partial \sigma(0, t)}{\partial x} \right|_{x=L} = -G, \quad t > 0 \\
IC: \quad & \sigma(x, 0) = \sigma_{nuc}(x, t_{nuc}), \quad t = 0
\end{aligned} \tag{2}$$

Here, L represents the length of the wire segment, and $\sigma_{nuc}(x, t_{nuc})$ denotes the stress distribution at the nucleation time t_{nuc} .

IV. PROPOSED BPINN-EM-POST FRAMEWORK FOR STOCHASTIC EM ANALYSIS

A. Estimation of Prior for BPINN

The overall framework of our proposed **BPINN-EM-Post** is shown in Fig. 1. A fully connected network serves as a surrogate model for our Bayesian physics-informed neural network (BPINN) framework, based on prior work [25], [29] and the demonstrated capability of Multi-layer Perceptron (MLP) architecture for this prediction task.

Let each layer of the network be denoted as $l = 1, 2, 3, \dots, L$ (where $L \geq 1$ is the number of layers). The output of the l^{th} layer, $\mathbf{z}_l \in \mathbb{R}^{N_l}$, is expressed as Eq. (3),

$$\mathbf{z}_l = \phi(\mathbf{w}_{l-1} \mathbf{z}_{l-1} + \mathbf{b}_{l-1}) \tag{3}$$

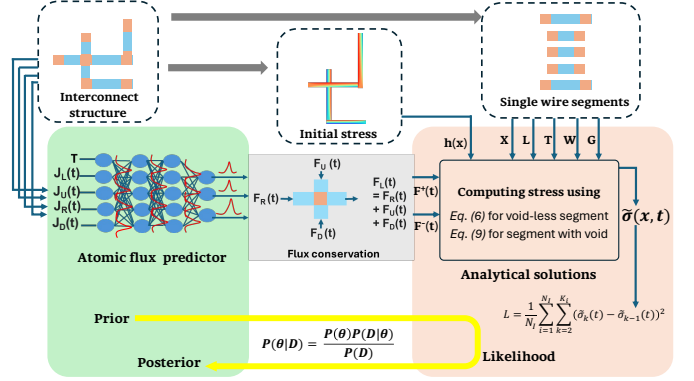


Fig. 1: Overall framework of the proposed **BPINN-EM-Post** variational EM simulator.

where ϕ is the non-linear activation function, $\mathbf{w} \in \mathbb{R}^{N_{l+1} \times N_l}$ represents weight matrices, and $\mathbf{b} \in \mathbb{R}^{N_{l+1}}$ denotes bias vectors. The network's output is given by Eq. (4),

$$\tilde{\mathbf{F}}(\mathbf{x}; \omega) = \mathbf{w}_L \mathbf{z}_L + \mathbf{b}_L \tag{4}$$

where \mathbf{x} is the input vector.

In this work, the Bayesian network processes information at all inter-segment junctions within a multi-segment interconnect structure. The input is $\mathbf{x} = \{T, J_L, J_U, J_R, J_D\}$, where T is the temporal vector (time information) and J_L, J_U, J_R, J_D are current densities for segments connected to the left, upper, right, and downward positions. The output $\tilde{\mathbf{F}}$ is 3-dimensional, with components $F_U, F_R,$ and F_D representing flux through the upper, right, and downward segments.

The unknown parameters ω comprise all weight matrices \mathbf{w} and bias vectors \mathbf{b} . For the BNN, ω is assigned a prior such that its components are independent Gaussian distributions with mean 0 and variances $\text{Var}_{w,l}$ and $\text{Var}_{b,l}$ for all layers [35]. As the hidden layer width approaches infinity, $\tilde{\mathbf{F}}(\mathbf{x})$ converges to a Gaussian process [35].

B. Generating Observations with Analytical Solutions

To generate stress solutions $\tilde{\sigma}(x, t; \omega)$ using $\tilde{\mathbf{F}}(\mathbf{x}; \omega)$, we adapt the analytical solutions proposed in [27]. Before using the output from the Bayesian network, $\tilde{\mathbf{F}}(\mathbf{x}; \omega)$, in the analytical solution, we perform linear transformations on it.

At any inter-segment junction of a multi-segment interconnect structure, up to four segments may connect. The three components of $\tilde{\mathbf{F}}$ represent flux information, which we denote as $F_U, F_R,$ and F_D , corresponding to the upper, right, and downward segments as shown in Fig. 1. A linear transformation is applied to compute the flux through the remaining segment. For example, flux through the left segment is calculated as $F_L = F_U + F_R + F_D$, enforcing atomic flux conservation, as described in Eq. (1).

Using flux information at each inter-segment junction, we calculate flux values F^- and F^+ at the endpoints of each segment within the multi-segment interconnect structure. The analytical solutions in *PostPINN-EM* [27] use these endpoint flux values to compute stress on single wire segments. Here,

F^- and F^+ represent flux at the left/down and right/upper positions, respectively.

As discussed in Sec. III, two types of segments exist in the post-voiding phase of a multi-segment interconnect structure: a voidless segments as in Fig. 2(a), and a segment containing a void at terminal as shown in Fig. 2(b). Given F^- and F^+ , stress $\tilde{\sigma}(x, t)$ at any location and time on a single wire segment can be accurately calculated.

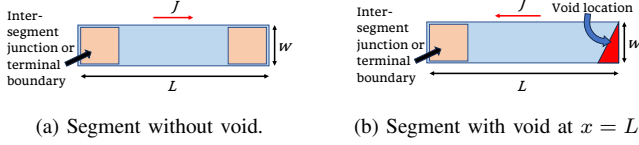


Fig. 2: Single interconnect segments that are part of a multi-segment interconnect tree in the post-voiding phase.

For analytical solutions, we define the stress gradient variables at the left or bottom node as $\phi^-(t)$ and at the right or top node as $\phi^+(t)$. Consequently, Korhonen's equation, modified with parametric BCs for wire segment without void is given in Eq. (5),

$$\begin{aligned}
 PDE : \frac{\partial \tilde{\sigma}(x, t)}{\partial t} &= \frac{\partial}{\partial x} \left[\kappa \left(\frac{\partial \tilde{\sigma}(x, t)}{\partial x} + G \right) \right], \quad t > 0, \quad 0 < x < L \\
 BC : \frac{\partial \tilde{\sigma}(x, t)}{\partial x} \Big|_{x=0} &= \phi^-(t), \\
 BC : \frac{\partial \tilde{\sigma}(x, t)}{\partial x} \Big|_{x=L} &= \phi^+(t), \\
 IC : \tilde{\sigma}(x, 0) &= \sigma_{nuc}(x, t_{nuc}) = h(x)
 \end{aligned} \tag{5}$$

In Eq. (5), $\tilde{\sigma}(x, t)$ represents the revised stress response from the updated Korhonen's equation, while $\phi^-(t)$ and $\phi^+(t)$ serve as tunable BCs reflecting the stress gradients at the boundaries. It is assumed that $h(x)$ characterizes the initial stress state, corresponding to the stress at the nucleation moment t_{nuc} . The solution to Eq. (5) can be effectively derived using the Laplace transformation method, resulting in the following analytical solution for $\tilde{\sigma}(x, t)$ in the time domain, as shown in Eq. (6),

$$\begin{aligned}
 \tilde{\sigma}(x, t) &= \sum_{p=0}^P \left\{ -\frac{d\phi^-(t)}{dt} * (g(\zeta_1(p, x, L), t) + g(\zeta_3(p, x, L), t)) \right. \\
 &\quad - \phi^-(0) (g(\zeta_1(p, x, L), t) + g(\zeta_3(p, x, L), t)) \\
 &\quad + \frac{d\phi^+}{dt} * (g(\zeta_2(p, x, L), t) + g(\zeta_4(p, x, L), t)) \\
 &\quad \left. + \phi^+(0) (g(\zeta_2(p, x, L), t) + g(\zeta_4(p, x, L), t)) \right\} \\
 &\quad + \frac{2}{L} \sum_{m=1}^M (-1)^m \left\{ e^{-M} \cos\left(\frac{m\pi x}{L}\right) \right. \\
 &\quad \left. \times \int_0^L h(u) \cos\left(\frac{m\pi(L-u)}{L}\right) du \right\}
 \end{aligned} \tag{6}$$

In this context, p and m are positive integers, with $0 \leq p \leq P$ and $1 \leq m \leq M$. It is recommended to maintain the three predominant components by setting $P = 2$ [26]. The value of M is established through experimental methods and is elaborately discussed in the results section. In Eq. (6), the convolution operator is denoted by $*$, which is defined as $a(t) * b(t) = \int_0^t a(\tau) b(t - \tau) d\tau$. This convolution is efficiently

executed using the Gauss-Legendre quadrature algorithm [26]. The functions $\zeta_1(p, x, L)$, $\zeta_2(p, x, L)$, $\zeta_3(p, x, L)$, $\zeta_4(p, x, L)$, and $g(x, t)$ are specified in Eq. (7) as follows,

$$\begin{aligned}
 \zeta_1(p, x, L) &= (2p + 2)L - x, \\
 \zeta_2(p, x, L) &= (2p + 1)L - x, \\
 \zeta_3(p, x, L) &= (2p)L + x, \\
 \zeta_4(p, x, L) &= (2p + 1)L + x, \\
 g(x, t) &= 2\sqrt{\frac{kt}{\pi}} e^{-\frac{x^2}{4kt}} - x \cdot \operatorname{erfc}\left\{\frac{x}{2\sqrt{kt}}\right\}
 \end{aligned} \tag{7}$$

For the segments with void, we assume that one end of the segment could either be an inter-segment junction or a terminal boundary, while the other end corresponds to a void node. Fig. 2(b) illustrates a single segment with a void at the $x = L$ end. At $x = 0$, which may represent either an inter-segment junction or a terminal boundary, a modifiable BC from the voidless scenario is applied. We modify the BC at $x = L$ to $\tilde{\sigma}(L, t) = 0$. When using a very small δ in Eq. (2), the BC at the site of the void mirrors the approach in [36]. The BCs for the segment with a void at the subsequent node of a wire segment, i.e., at $x = L$, are expressed as Eq. (8),

$$\begin{aligned}
 BC : \frac{\partial \tilde{\sigma}(x, t)}{\partial x} \Big|_{x=0} &= \phi^-(t) \\
 BC : \tilde{\sigma}(x, t) \Big|_{x=L} &= 0
 \end{aligned} \tag{8}$$

Similar to the solution for the segment without a void, the solution for the single segment with a void location at $x = L$ is derived using the Laplace transform method as shown below in Eq. (9),

$$\begin{aligned}
 \tilde{\sigma}(x, t) &= \sum_{p=0}^P (-1)^p \left\{ \frac{d\phi^-(t)}{dt} * (g(\zeta_1(p, x, L), t) - g(\zeta_3(p, x, L), t)) \right. \\
 &\quad + \phi^-(0) (g(\zeta_1(p, x, L), t) - g(\zeta_3(p, x, L), t)) \\
 &\quad + \frac{2}{L} \sum_{m=1}^M (-1)^{m+1} \left\{ e^{-M} \cos\left(\frac{(m-0.5)\pi x}{L}\right) \right. \\
 &\quad \left. \times \int_0^L h(u) \sin\left(\frac{(m-0.5)\pi(L-u)}{L}\right) du \right\}
 \end{aligned} \tag{9}$$

Similarly, when the void is positioned at the preceding (left/bottom) end, i.e., at $x = 0$, the BC is defined as $\tilde{\sigma}(x, t) = 0$ at $x = 0$ and $\frac{\partial \tilde{\sigma}(x, t)}{\partial x} = \phi^+(t)$ at $x = L$. Using the same Laplace transform method, the analytical solution for this scenario can also be derived. In Eq. (6) and Eq. (9) the values $\phi^-(0)$ and $\phi^+(0)$ can be calculated using the current density information at each inter-segment junctions [26], [27]. For each single segment, we use the flux information from Bayesian network as $\frac{d\phi^-(t)}{dt} = F^-(\mathbf{x}; \omega)$ and $\frac{d\phi^+(t)}{dt} = F^+(\mathbf{x}; \omega)$.

The analytical solutions in Eq. (6) and Eq. (9) estimate the stress distribution for single segments within a multi-segment interconnect structure, given the flux information. For accurate stress distribution, all relevant physical conditions must be satisfied. While calculating the flux information, atomic flux conservation was enforced. Additionally, as per Eq. (1), stress continuity must be maintained at inter-segment junctions. This implies that the stress in all segments connected to a junction should be equal.

To ensure stress continuity, we optimize the BPINN using the stress continuity condition \mathcal{L} , which is defined in Eq. (10),

$$\mathcal{L} = \frac{1}{N_I \times K_i} \sum_{i=1}^{N_I} \sum_{k=2}^{K_i} (\tilde{\sigma}_k(x_\sigma; \omega) - \tilde{\sigma}_{k-1}(x_\sigma; \omega))^2 \quad (10)$$

where $\tilde{\sigma}_k(\omega)$ represents the EM stress at the boundary of the k^{th} segment at inter-segment junction i , K_i is the number of segments connected to junction i , and N_I is the total number of inter-segment junctions in the multi-segment structure. Since $\tilde{\sigma}$ depends on $F^-(\mathbf{x}; \omega)$ and $F^+(\mathbf{x}; \omega)$, it is expressed as a function of ω and the parameters influencing stress, denoted as x_σ , for simplicity.

C. Evaluation of Posterior for BPINN

In this work, the Bayesian network takes temporal and current information at each inter-segment junction of the multi-segment interconnect structure as input, i.e., $\mathbf{x} = \{T, J_L, J_U, J_R, J_D\}$. Using the flux information from the network's output, we enforce atomic flux conservation to calculate the flux values $F^-(\mathbf{x}; \omega)$ and $F^+(\mathbf{x}; \omega)$ at the endpoints of each segment.

The analytical solutions use these flux values, along with geometric and electrical properties of the wires, to compute the stress $\tilde{\sigma}(x, t)$. To ensure accurate stress predictions, we incorporate stress observations at the boundaries of each wire segment to construct a loss function \mathcal{L} . This function is used to optimize the Bayesian network's parameters, yielding flux information that satisfies both atomic flux conservation and stress continuity at wire segment boundaries.

Therefore, for this case we can define the dataset as Eq. (11),

$$\mathcal{D} = \left\{ \mathbf{x}^{(i)}, \tilde{\mathcal{L}}^{(i)} \right\}_{i=1}^{N_{\mathcal{L}}} \quad (11)$$

here we assume that the observations are variational, and can be represented as in Eq. (12),

$$\tilde{\mathcal{L}} = \mathcal{L}(x_{\mathcal{L}}^{(i)}; \omega) + \epsilon^{(i)}, i = 1, 2, 3, \dots, N_{\mathcal{L}} \quad (12)$$

where ϵ is independent Gaussian noise with zero mean and variance of $\text{Var}_{\mathcal{L}}$. The likelihood of the observations can be calculated as Eq. (13),

$$P(\mathcal{D}|\omega) = \prod_{i=1}^{N_{\mathcal{L}}} \frac{1}{\sqrt{2\pi \text{Var}_{\mathcal{L}}^{(i)}}} \times \exp \left[-\frac{(\mathcal{L}(x_{\mathcal{L}}^{(i)}; \omega) - \tilde{\mathcal{L}}^{(i)})^2}{2\text{Var}_{\mathcal{L}}^{(i)}} \right] \quad (13)$$

Utilizing this likelihood, the posterior can be obtained as,

$$P(\omega|\mathcal{D}) = \frac{P(\mathcal{D}|\omega)P(\omega)}{P(\mathcal{D})} \propto P(\mathcal{D}|\omega)P(\omega) \quad (14)$$

here the symbol \propto signifies 'equality up to a constant'. The probability of the dataset $P(\mathcal{D})$ is not readily solvable through analytical methods. Therefore, in practical scenarios, we only obtain an un-normalized expression $P(\omega|\mathcal{D})$.

This work **BPINN-EM-Post** employs the Hamiltonian Monte Carlo (HMC) method to navigate the parameter space of our BNN model. HMC is a gradient-based Markov Chain Monte Carlo (MCMC) technique that utilizes Hamiltonian dynamics for parameter exploration. Our HMC procedure

begins by simulating Hamiltonian dynamics through a numerical integration method, followed by a correction using the Metropolis-Hastings acceptance step. Given a dataset \mathcal{D} , we postulate the target posterior distribution for ω as shown in Eq. (15),

$$P(\omega|\mathcal{D}) \simeq \exp(-U(\omega)) \quad (15)$$

where $U(\omega) = -\log(P(\mathcal{D}|\omega)) - \log(P(\omega))$ serves as the potential energy in the system. To sample from the posterior distribution, HMC introduces an auxiliary momentum variable r , which is used to formulate a Hamiltonian system as,

$$H(\omega, r) = U(\omega) + \frac{1}{2} r^T M^{-1} r \quad (16)$$

Here, M is a mass matrix usually set as identity matrix. HMC then generates samples from the joint distribution of (ω, r) as,

$$\pi(\omega, r) \sim \exp(-U(\omega) - \frac{1}{2} r^T M^{-1} r) \quad (17)$$

where the samples of ω have a marginal distribution as we discard the samples of r . These samples are derived from the following Hamiltonian dynamics as in Eq. (18),

$$d\omega = M^{-1} r dt, \quad dr = -\nabla U(\omega) dt \quad (18)$$

Eq. (18) is discretized through the leapfrog method, and the Metropolis-Hastings step is employed to minimize the discretization error. More implementation details on the HMC algorithm are explained in [35].

D. Estimation of Variations in EM Stress

Using HMC, we sample the optimal Bayesian network parameters, ω , to generate samples of flux information, $\{\tilde{\mathbf{F}}(\mathbf{x}; \omega^{(i)})\}_{i=1}^M$. From these, we derive samples of $\{\mathbf{F}^-\}$ and $\{\mathbf{F}^+\}$. For each wire segment, these flux samples are used to compute M stress solution samples, $\{\tilde{\sigma}(x, t)\}$.

Notably, when obtaining the optimal parameter samples via HMC, we utilize only stress observations at the boundaries of single wire segments within the multi-segment interconnect structure. This significantly reduces the variables in the loss function \mathcal{L} , enabling efficient training. Once the framework is fully trained and optimal parameters are obtained, we calculate the flux information at all wire segment boundaries. This flux information is termed optimal as it satisfies flux conservation and stress continuity at inter-segment junctions. Using the optimal flux information samples, we compute accurate stress distribution samples for individual segments through analytical solutions. Additionally, variations in stress solutions, such as mean and standard deviation, are estimated from the calculated stress samples.

V. EXPERIMENTAL RESULTS

A. Experimental Setup

The proposed **BPINN-EM-Post** framework is fully developed using Python/PyTorch. The training and test procedures are conducted on a Linux server equipped with two Intel 22-core E5-2699 CPUs, 320 GB of memory, and an Nvidia

TITAN RTX GPU. A three-layer MLP with layer structure [15-FC50-FC50-O3] is used in BPINN flux predictor.

B. Data Preparation and Scaling

To determine the stress distribution in a multi-segment interconnect structure, we first gather the physical and material attributes of the interconnect segments. Each segment i is characterized by its physical properties, including length L_i and width w_i , while assuming uniform thermal conductivity κ across all segments. Spatial points x are sampled within $[0, L]$, and temporal points are chosen from $t = 0$ to 1×10^9 s at intervals of 1×10^7 s. In this analysis, we incorporate the nucleation-phase solutions for these interconnects that are easily pre-established by existing methods [13], [17], [29] consistent to this work, providing initial stress distribution $h(x)$ and void locations.

The input parameters for the analytical method and the MLP vary significantly in scale, necessitating data scaling for standardization. Scaling factors k_x , k_t , and k_σ are used for spatial (x), temporal (t) and stress (σ), respectively. Additional parameters are processed in Eq. (19),

$$\begin{aligned} k_\sigma \sigma(x, t, \kappa, G) &= \sigma_{sc}(x_{sc}, t_{sc}, \kappa_{sc}, G_{sc}) \\ &= \sigma_{sc}(k_x x, k_t t, \frac{k_x^2}{k_t} \kappa, \frac{k_\sigma}{k_x} G) \end{aligned} \quad (19)$$

where x_{sc} , t_{sc} , κ_{sc} , G_{sc} , and σ_{sc} are the scaled versions of x , t , κ , G , and σ , respectively. The scaled stress σ_{sc} is converted back to its original scale using k_σ . In this study, scaling constants are set as $k_x = 1 \times 10^{-5}$, $k_t = 1 \times 10^{-7}$, and $k_\sigma = 1 \times 10^{-8}$.

To assess the accuracy and performance of our proposed **BPINN-EM-Post**, we compare results against Monte Carlo simulations using FEM-based COMSOL [17] and FDM-based EMSpice tool [13]. For each Monte Carlo iteration, branch currents are randomly sampled from a normal distribution with a mean range of 5×10^{-8} A/m² to 5×10^9 A/m² to introduce variability to input currents.

C. Accuracy and Performance of Analytical Solutions

In order to evaluate the precision and speed of the analytical solutions, we conducted comparisons with results from COMSOL simulations using a variety of specific stress gradients. We randomly generated 500 single wire segments samples, with lengths varying from $10 \mu\text{m}$ to $50 \mu\text{m}$, all maintaining a uniform width of $1 \mu\text{m}$. These segments were subjected to current densities spanning from -5×10^9 A/m² to 5×10^{10} A/m². Other physical parameters are set as $e = 1.6 \times 10^{-19}$ C, $Z^* = 10$, $E_a = 1.1$ eV, $B = 1 \times 10^{11}$, $D_0 = 5.2 \times 10^{-5}$ m²/s, $\rho = 2.2 \times 10^{-8}$ Ωm , $\Omega = 8.78 \times 10^{-30}$ m³, and $\sigma_{crit} = 5 \times 10^8$ Pa. In the evaluation of our analytical solutions, the wire segments were modeled with non-zero boundary flux to represent their placement within the multi-segment trees. For each segment, we collected data at 30 spatial positions $x \in [0, L]$ and across 100 time intervals from 0 to 1×10^8 seconds to account for aging time t . These segments were individually analyzed using COMSOL and benchmarked against our analytical solution. We employed the root mean square error (RMSE) to measure

discrepancies, noting that the stress values $\sigma(x, t)$ ranged from -1.1×10^8 to 4.6×10^8 Pa. With our analytical approach, we achieved an **average RMSE of 3.3×10^4** Pa, correlating to an **average error margin of 0.006%**. The analytical solver recorded an average processing time of 0.01 seconds per segment, in stark contrast to COMSOL's 7.5 seconds, resulting in a **computational speedup of approximately 750 \times** . This demonstrates that our first-stage analytical solver delivers both rapid and precise results when juxtaposed with FEM-based COMSOL simulations.

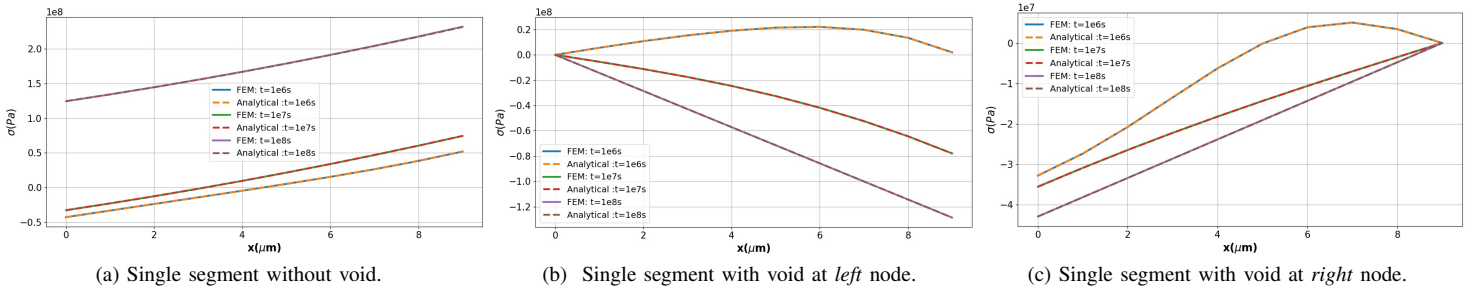
Fig. 3 illustrates the comparative results of our analytical solution versus COMSOL for segments with and without voids, achieved with $M = 5$ in the analytical calculations, which was decided by experimental determination and consistently applied throughout this study.

D. Overall Accuracy and Performance Analysis

To assess the efficacy and precision of our method across a variety of general multi-segment interconnect structures, we analyzed a total of 1000 randomly generated configurations, each containing between 50 and 250 segments, with each inter-segment junction connected to at most four segments. These structures were examined to gauge variational EM stress through the use of COMSOL [17], EMSpice [13], and our proposed **BPINN-EM-Post**, utilizing 30 samples to measure variations in stochastic EM stress. We should notice that other existing works [25], [27] are not applicable for stochastic analysis, while [29] cannot be employed in post-voiding phase, thus these methods are not available for numerical comparison. The findings, detailing accuracy and performance metrics for multi-segment interconnect structures across different segment counts, are showcased in Tab. I. Our method exhibits superior acceleration than prior arts, with error rate of only 1.10% at most, compared with COMSOL and less than 0.2% compared with EMSpice. In addition, Training and Inference time shows nearly linear growth with respect to the number of wires, indicating its scalability to larger interconnect structures.

The observed range of EM stress across these structures spanned from -4.31×10^9 Pa to 5.94×10^9 Pa. Accuracy was quantified using RMSE defined as $RMSE = (RMSE_{mean} + RMSE_{std})/2$. For dataset comprising 1000 multi-segment interconnect structures, the average RMSE relative to COMSOL stood at 7.07×10^7 Pa, equating to an error margin around 0.69%. In comparison, against EMSpice, the average RMSE was recorded at 9.5×10^6 Pa, reflecting an error rate about 0.093%.

Fig. 4 demonstrates the variations in EM stress, expressed through both mean and standard deviation, for a ten-segment interconnect structure for simplicity. The physical and electrical characteristics of which are shown in Fig. 4(a). The variations in EM stress at the selected junctions between segments of this interconnect structure are detailed in Fig. 4(b), Fig. 4(c), Fig. 4(d), and Fig. 4(e). In these comparisons, our proposed **BPINN-EM-Post** is shown to precisely predict the variations in EM stress, aligning closely with the results obtained from COMSOL [17] and EMSpice [13].



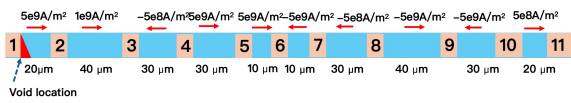
(a) Single segment without void.

(b) Single segment with void at *left* node.(c) Single segment with void at *right* node.

Fig. 3: Comparison of the stress distribution obtained from analytical solution with the stress distribution from FEM-based COMSOL for single interconnect segment for three different cases.

TABLE I: Performance and accuracy comparisons with existing methods [17], [13].

# of wires	COMSOL [17]	EMSpice [13]	The Proposed <i>BPINN-EM-Post</i>					
	Runtime	Runtime	Error v.s. COMSOL	Error v.s. EMSpice	Training time	Inference time	Speedup v.s. COMSOL	Speedup v.s. EMSpice
50	2560s	876s	0.25%	0.051%	6.5s	0.52s	364.67× ↑	124.79× ↑
100	4800s	1490s	0.31%	0.074%	15.3s	0.71s	299.81× ↑	93.07× ↑
150	6731s	2122s	0.52%	0.094%	21.8s	0.91s	296.39× ↑	93.44× ↑
200	9230s	3100s	0.74%	0.126%	37.9s	1.25s	235.76× ↑	79.18× ↑
250	10191s	3656s	1.10%	0.163%	55.6s	1.51s	178.45× ↑	64.02× ↑



(a) Ten-segment interconnect structure. Depicted current densities are the mean values of the current densities used during simulation.

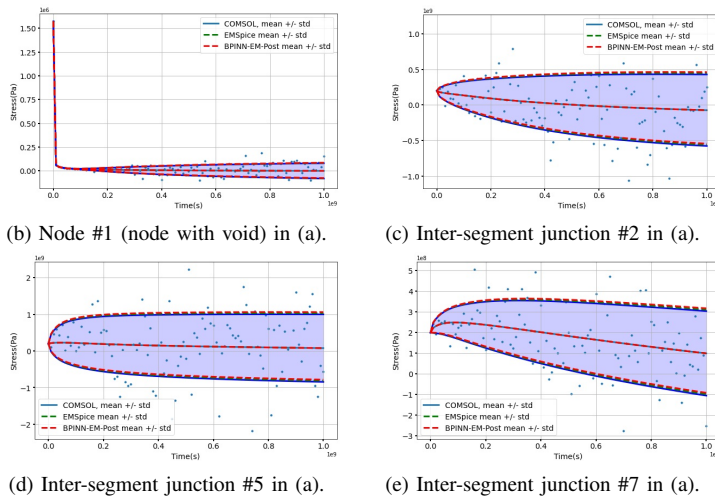
multi-segment interconnects assessed, the average runtime for *BPINN-EM-Post* is noted to be approximately 31 seconds, significantly accelerating the estimation process by a factor of 240× faster than COMSOL and 67× quicker than EMSpice. This efficiency marks our approach as vastly superior in terms of speed for calculating variational EM stress.

VI. CONCLUSION

In this paper, we introduced *BPINN-EM-Post*, a novel machine learning-based stochastic analysis framework for efficient variational Electromigration (EM)-induced stress estimation. Our key contributions include: (1) A hybrid approach combining closed-form analytical solutions with PINNs, which avoids modeling complex initial stress distributions by leveraging analytical solutions for individual wire segments; (2) A physics-constrained inter-segment formulation that enforces stress continuity and atomic flux conservation through the neural network, significantly reducing the number of variables in the loss function and accelerating training; (3) A Bayesian extension that provides built-in uncertainty quantification, enabling efficient variational analysis without costly Monte Carlo sampling. Experimental results validate the effectiveness of our framework, achieving a 240× speedup over FEM-based Monte Carlo simulations and a 67× acceleration compared to FDM-based methods, while maintaining accuracy. These results demonstrate that *BPINN-EM-Post* offers a scalable and reliable solution for variational EM stress analysis in modern interconnect reliability assessment.

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(b) Node #1 (node with void) in (a).

(c) Inter-segment junction #2 in (a).

(d) Inter-segment junction #5 in (a).

(e) Inter-segment junction #7 in (a).

Fig. 4: Illustration of stress variations at junctions of a multi-segment interconnect structure. (a): Example of a ten-segment interconnect. (b), (c), (d), (e): Comparisons of variations estimation between the proposed framework, COMSOL and EMSpice at different junctions.

In the analysis of stochastic EM stress variances for multi-segment interconnect structures, COMSOL's average runtime for 1000 multi-segment interconnect structures is approximately 7500 seconds, while EMSpice takes about 2100 seconds in average. For *BPINN-EM-Post*, variations in stochastic EM stress are estimated by sampling from the BNN via HMC. Prior to this, the analytical solutions must ascertain the optimal atomic flux at the termini of each segment within the structures, leveraging a PINN. Thus, both the sampling (training) period of the PINN and the inference duration of the BNN are accounted for in the runtime evaluation. For the

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